EFB24-SR N4 - Damper Actuator

NEMA 4, Modulating, Spring Return, 24 V, for 2 or 10 VDC or 4 to 20 mA Control Signal











Technical Data Power Supply 24 VAC±20%, 50/60Hz, 24 VDC±20%/-10% Power Consumption Running 8 W Power Consumption Holding 4.5 W Transformer Sizing 14 VA (class 2 power source) Shaft Diameter 1/2" to 1.05" round, centers on 3/4" with insert, 1.05" without insert Electrical Connection terminal block(s) inside junction box with knockouts Overload Protection electronic throughout 0° to 95° rotation Electrical Protection actuators are double insulated Operating Range Y 2 to 10 VDC, 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 Input Impedance 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA Feedback Output U 2 to 10 VDC, 0.5 mA max Angle of Rotation max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) 270 in-lbs [30 Nm] minimum Direction of Rotation (Motor) reversible with built-in switch Direction of Rotation (Fail-Safe) reversible with CW/CCW mounting Position Indication visual indicator, 0° to 95° (0° is full spring return position) Manual Override 5 mm hex crank (3/16" Allen), supplied Running Time (Motor) 95 sec </th <th></th> <th>REG. EQUIP.</th>		REG. EQUIP.
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Transformer Sizing 14 VA (class 2 power source) Shaft Diameter 1/2" to 1.05" round, centers on 3/4" with insert, 1.05" without insert Electrical Connection terminal block(s) inside junction box with knockouts Overload Protection Electrical Protection Operating Range Y 2 to 10 VDC, 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 Input Impedance 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA Feedback Output U 2 to 10 VDC, 0.5 mA max Angle of Rotation max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) Direction of Rotation (Motor) Direction of Rotation (Fail-Safe) Position Indication Manual Override S mm hex crank (3/16" Allen), supplied Running Time (Motor) Running Time (Fail-Safe) V=20 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C] Humidity Ambient Temperature Range Above to 176°F [-40°C to 80°C] Housing NEMA 4, IP66, UL enclosure type 4 Housing Material Aluminum die cast and plastic casing Agency Listings† CULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) Servicing Maintenance free Quality Standard ISO 9001	Power Consumption Running	8 W
Shaft Diameter 1/2" to 1.05" round, centers on 3/4" with insert, 1.05" without insert Electrical Connection terminal block(s) inside junction box with knockouts Overload Protection electronic throughout 0° to 95° rotation Electrical Protection Operating Range Y 2 to 10 VDC, 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 Input Impedance 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA Feedback Output U 2 to 10 VDC, 0.5 mA max Angle of Rotation max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) Direction of Rotation (Motor) Direction of Rotation (Fail-Safe) Position Indication Manual Override Running Time (Motor) Bunning Time (Fail-Safe) 420 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C] Humidity Ambient Temperature Range -40°F to 176°F [-40°C to 80°C] Housing Agency Listings† CULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) ≤56.5 dB (A) Noise Level (Fail-Safe) Verload Protection terminal block(s) inside junction box with knockouts insert are double insulated insulated 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω, 1/2 W resistor) ZG-R01 To 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω,	Power Consumption Holding	4.5 W
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Electrical Connection terminal block(s) inside junction box with knockouts Overload Protection electronic throughout 0° to 95° rotation Electrical Protection actuators are double insulated Operating Range Y 2 to 10 VDC, 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 Input Impedance 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA Feedback Output U 2 to 10 VDC, 0.5 mA max Angle of Rotation max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) 270 in-lbs [30 Nm] minimum Direction of Rotation (Motor) reversible with built-in switch Direction of Rotation (Fail-Safe) reversible with CW/CCW mounting Position Indication visual indicator, 0° to 95° (0° is full spring return position) Manual Override 5 mm hex crank (3/16" Allen), supplied Running Time (Motor) 95 sec Running Time (Fail-Safe) <20 sec @ -4°F to 122°F [-30°C]	Shaft Diameter	
Electrical Protection actuators are double insulated Operating Range Y 2 to 10 VDC, 4 to 20 mA (w/ 500 Ω, 1/2 W resistor) ZG-R01 Input Impedance $100 \text{ k } \Omega$ for 2 to 10 VDC (0.1 mA), 500Ω for 4 to 20 mA Feedback Output U $2 \text{ to } 10 \text{ VDC}$, 0.5 mA max Angle of Rotation \max . 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) $270 \text{ in-lbs } [30 \text{ Nm}] \text{ minimum}$ Direction of Rotation (Motor) reversible with built-in switch Direction of Rotation (Fail-Safe) reversible with CW/CCW mounting Position Indication visual indicator, 0° to 95° (0° is full spring return position) Manual Override 5 mm hex crank (3/16" Allen), supplied Running Time (Motor) 95 sec Running Time (Fail-Safe) <20 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C]	Electrical Connection	terminal block(s) inside junction box with
Operating Range Y2 to 10 VDC, 4 to 20 mA (w/ 500 Ω , 1/2 W resistor) ZG-R01Input Impedance100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mAFeedback Output U2 to 10 VDC, 0.5 mA maxAngle of Rotationmax. 95° (adjustable with mechanical end stop, 35° to 95°)Torque (US unit)270 in-lbs [30 Nm] minimumDirection of Rotation (Motor)reversible with built-in switchDirection of Rotation (Fail-Safe)reversible with CW/CCW mountingPosition Indicationvisual indicator, 0° to 95° (0° is full spring return position)Manual Override5 mm hex crank (3/16" Allen), suppliedRunning Time (Motor)95 secRunning Time (Fail-Safe)<20 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C]	Overload Protection	electronic throughout 0° to 95° rotation
$\begin{array}{c} \text{resistor) ZG-R01} \\ \text{Input Impedance} & 100 \text{ k} \ \Omega \text{ for 2 to 10 VDC (0.1 mA), 500 } \Omega \text{ for 4 to 20 mA} \\ \text{Feedback Output U} & 2 \text{ to 10 VDC, 0.5 mA max} \\ \text{Angle of Rotation} & \max. 95^{\circ} \text{ (adjustable with mechanical end stop, 35^{\circ} to 95^{\circ})} \\ \text{Torque (US unit)} & 270 \text{ in-lbs [30 Nm] minimum} \\ \text{Direction of Rotation (Motor)} & \text{reversible with built-in switch} \\ \text{Direction of Rotation (Fail-Safe)} & \text{reversible with CW/CCW mounting} \\ \text{Position Indication} & \text{visual indicator, 0^{\circ} to 95^{\circ} (0^{\circ} \text{ is full spring return position)}} \\ \text{Manual Override} & 5 \text{ mm hex crank (3/16" Allen), supplied} \\ \text{Running Time (Motor)} & 95 \text{ sec} \\ \text{Running Time (Fail-Safe)} & <20 \text{ sec} @ -4^{\circ}\text{F to 122^{\circ}\text{F} [-20^{\circ}\text{C to 50^{\circ}\text{C}]}} < 60 \text{ sec} @ -22^{\circ}\text{F} [-30^{\circ}\text{C}]} \\ \text{Humidity} & 100\% \text{ condensing} \\ \text{Ambient Temperature Range} & -40^{\circ}\text{F to 176^{\circ}\text{F} [-40^{\circ}\text{C to 80^{\circ}\text{C}]}} \\ \text{Housing} & \text{NEMA 4, IP66, UL enclosure type 4} \\ \text{Housing Material} & \text{Aluminum die cast and plastic casing} \\ \text{Agency Listings} \dagger & \text{cULus acc. to UL60730-1A/-2-14, CAN/CSA} \\ \text{E60730-1:02, CE acc. to 2004/108/EC} \\ \text{Noise Level (Motor)} & \leq 56.5 \text{ dB (A)} \\ \text{Servicing} & \text{maintenance free} \\ \text{Quality Standard} & \text{ISO 9001} \\ \end{array}$	Electrical Protection	actuators are double insulated
4 to 20 mA Feedback Output U 2 to 10 VDC, 0.5 mA max Angle of Rotation max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) Direction of Rotation (Motor) Direction of Rotation (Fail-Safe) Position Indication Manual Override Running Time (Motor) Running Time (Fail-Safe) Humidity Ambient Temperature Range Storage Temperature Range Agency Listings† 4 to 20 mA 2 to 10 VDC, 0.5 mA max max. 95° (adjustable with mechanical end stop, 35° to 95°) Torque (US unit) 270 in-lbs [30 Nm] minimum preversible with CW/CCW mounting reversible with CW/CCW mounting visual indicator, 0° to 95° (0° is full spring return position) Manual Override 5 mm hex crank (3/16" Allen), supplied 8 col sec @ -4°F to 122°F [-20°C to 50°C], < 60 sec @ -22°F [-30°C] 100% condensing Ablient Temperature Range -40°F to 176°F [-40°C to 80°C] Housing NEMA 4, IP66, UL enclosure type 4 Housing Material Aluminum die cast and plastic casing Agency Listings† CULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) Servicing maintenance free Quality Standard ISO 9001	Operating Range Y	, , , , , , , , , , , , , , , , , , , ,
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Running Time (Fail-Safe) <pre></pre>	Manual Override	
60 sec @ -22°F [-30°C] Humidity	Running Time (Motor)	95 sec
Ambient Temperature Range -22°F to 122°F [-30°C to 50°C] Storage Temperature Range -40°F to 176°F [-40°C to 80°C] Housing NEMA 4, IP66, UL enclosure type 4 Housing Material Aluminum die cast and plastic casing Agency Listings† cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) ≤56.5 dB (A) Noise Level (Fail-Safe) ≤71 dB (A) Servicing maintenance free Quality Standard ISO 9001	Running Time (Fail-Safe)	
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Housing NEMA 4, IP66, UL enclosure type 4 Housing Material Aluminum die cast and plastic casing Agency Listings† CULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) ≤56.5 dB (A) Noise Level (Fail-Safe) ≤71 dB (A) Servicing maintenance free Quality Standard ISO 9001	Ambient Temperature Range	-22°F to 122°F [-30°C to 50°C]
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E60730-1:02, CE acc. to 2004/108/EC Noise Level (Motor) ≤56.5 dB (A) Noise Level (Fail-Safe) ≤71 dB (A) Servicing maintenance free Quality Standard ISO 9001	Housing Material	Aluminum die cast and plastic casing
Noise Level (Motor) ≤56.5 dB (A) Noise Level (Fail-Safe) ≤71 dB (A) Servicing maintenance free Quality Standard ISO 9001	Agency Listings†	
Servicing maintenance free Quality Standard ISO 9001	Noise Level (Motor)	
Quality Standard ISO 9001	Noise Level (Fail-Safe)	≤71 dB (A)
	Servicing	maintenance free
Weight 10 lbs [4.54 kg]	Quality Standard	1.00
	Weight	10 lbs [4.54 kg]

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 4.

Torque min. 270 in-lb, for control of air dampers

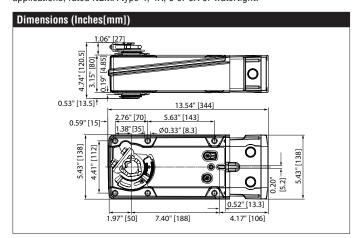
Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

Operation

The EF..24-SR N4 series actuators provide true spring return operation for reliable failsafe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The EF..24-SR N4 series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The EF..24-SR N4 uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF..24-SR N4 actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Installation Note: Use 60°C/75°C copper (CU) conductor and wire size range 12-26 AWG, stranded or solid. If conduit is used, use flexible metal conduit; UL listed and CSA certified strain relief or conduit fitting suitable for outdoor applications, rated NEMA type 4, 4X, 6 or 6X or watertight.



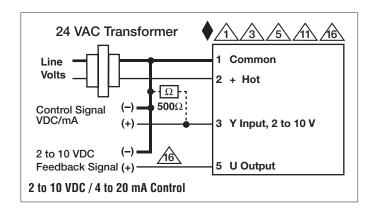
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NEMA 4, Modulating, Spring Return, 24 V, for 2 or 10 VDC or 4 to 20 mA Control Signal

Accessorie		
AV8-25	9.8" shaft extension for 5/16" to 1" diameter shafts.	
EF-P	Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).	
IND-EFB	EFB(X) position indicator.	
K9-2	Standard EFB(X) clamp (1/2" to 1.05").	
KG10A	Ball joint for 3/8" diameter rod, zinc plated.	
KH10	Univ. crankarm, slot 21/64" w, for 9/16" to 1" dia. shafts.	
KH-EFB	EFB(X) crankarm (with 1.05" diameter shaft pass through).	
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).	
T00L-07	13 mm wrench.	
ZG-100	Univ. right angle bracket (17" H x 11-1/8" W x 6" base).	
ZG-120	Jackshaft mounting bracket.	
ZG-DC1	Damper clip for damper blade, 3.5" width.	
ZG-DC2	Damper clip for damper blade, 6" width.	
ZG-EFB	EFB(X) crankarm adaptor kit.	
ZG-JSA-3	1.05" diameter jackshaft adaptor (12" L).	
ADS-100	Analog to digital switch for modulating actuators.	
IRM-100	Input rescaling module for modulating actuators.	
PS-100	Actuator power supply and control simulator.	
PTA-250	Pulse width modulation interface for modulating actuators.	
SGA24	Positioner control for modualting actuators (surface mount).	
SGF24	Positioner control for modulating actuators (flush mount).	
ZG-R01	4 to 20 mA adaptor, 500Ω , $1/4$ W resistor w 6" pigtail wires.	
ZG-R02	50% voltage divider kit (resistors with wires).	
ZG-SGF	Mounting plate for SGF.	
ZG-X40	120 to 24 VAC, 40 VA transformer.	

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



EFB24-SR N4 - Damper Actuator



NEMA 4, Modulating, Spring Return, 24 V, for 2 or 10 VDC or 4 to 20 mA Control Signal

Wiring Diagrams



WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Only connect common to negative (-) leg of control circuits.



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



Actuators are provided with a numbered screw terminal strip instead of a cable.